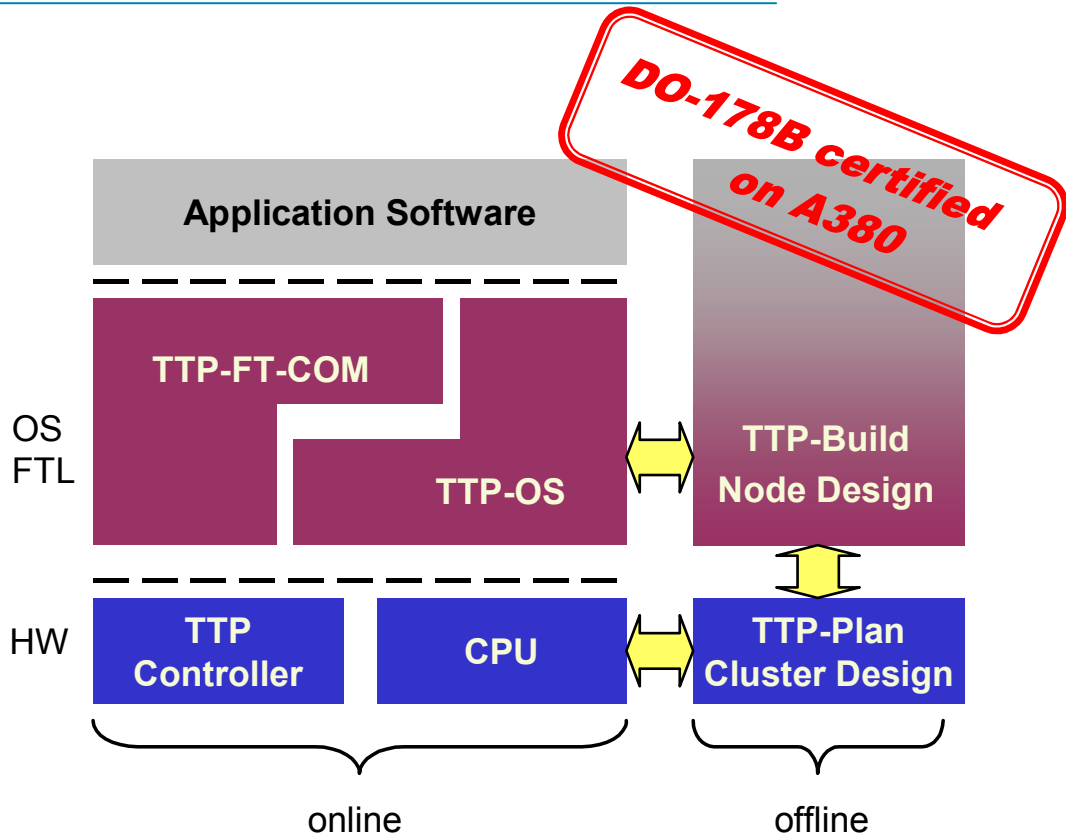


Operating System for Fault-Tolerance and Real-Time



^{TTP}OS – Time-Triggered RTOS with TTP Support

^{TTP}OS is a real-time operating system (RTOS) specifically designed for fault-tolerant real-time applications based on Time-Triggered Technology. It has a very small footprint and offers fast services and task switching. ^{TTP}OS provides time-triggered pre-emptive task scheduling and is based on OSEKtime. In addition, ^{TTP}OS supports fast error detection and fault tolerance. ^{TTP}OS was developed according to the RTCA software standard DO-178B Level A.

Execution of Application Tasks

Tasks responsible for the communication abstraction and fault-tolerant behavior (^{TTP}FT-COM) are executed on the basis of the global time provided by the TTP® communications controller. Other application tasks can use a local timer, which is provided by ^{TTP}OS and synchronized with the global time.

OSEKtime Compliance

^{TTP}OS is based on the OSEKtime working group specifications for the OSEK/VDX operating system. ^{TTP}OS is a bridge between the OSEK/VDX specification and the world of Time-Triggered Technology.

Tool-Based Configuration

The TTP node design Tool ^{TTP}Build provides fully automatic configuration for ^{TTP}OS and optimized code generation for the fault-tolerant communication (^{TTP}FT-COM) layer. ^{TTP}Build generates ANSI C code for the ^{TTP}FT-COM that allows easy integration with a broad variety of embedded system platforms.

Functionality

- ROM-able kernel with very small footprint: ROM requirements for Freescale MPC555 PowerPC® approximately 9kB, RAM requirements independent of application size approximately 352 Bytes
- Extremely efficient CPU utilization
- Based on OSEK/VDX specification
- Dispatcher compliant with OSEKtime standard
- Startup and re-integration to TTP communication system
- Pre-emptive scheduling strategy
- Deadline monitoring for tasks
- Interrupt service handlers for aperiodic tasks
- Timetable-driven scheduling with support for multiple time bases (e.g. global fault-tolerant TTP time, local time)
- TTP multiplexing support
- Support for austriamicrosystems AS8202NF (C2NF) TTP communication controller
- Developed according to the RTCA software standard DO-178B Level A

Features of the Fault-Tolerant Communication Layer (TTP^{FT-COM})

- Message/frame mapping
- Packing/unpacking
- Handling of replicated redundant message instances
- Bit-sized messages
- Message stability
- Message agreement (replica determinism)
- Application-specific agreement algorithms
- Byte ordering (endianess)
- Sender status
- Re-integration (history state handling)
- Standard ANSI C code

Supported Platforms

- Freescale MPC555 PowerPC for austriamicrosystems AS8202NF (C2NF) communication controller
- Other platforms such as Infineon C167 for austriamicrosystems AS8202NF (C2NF) communication controller, NEC V850E for austriamicrosystems AS8202NF (C2NF) communication controller and more are available upon request

The TTP^{Tools} Software Development Suite

TTP^{OS} is part of the TTP^{Tools} development suite. The other components of TTP^{Tools} are:

- TTP^{Matlink} – The TTP Simulation and Design Tool
- TTP^{Plan} – The TTP Cluster Design Tool
- TTP^{Build} – The TTP Node Design Tool
- TTP^{Load} – The TTP Download Tool
- TTP^{View} – The TTP Real-Time Monitoring Tool

Subject to changes and corrections.

For further information, including price and availability, contact products@tttech.com.

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